

Exploring integral-type theorems through fixed-point iteration with C-class functions

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ABSTRACT. In this paper, the concept of C-class functions is used to establish the existence and uniqueness of a fixed point for a self-map of integral type within a complete metric space. The theoretical foundation is presented and the results are exemplified through a specific case. Lastly, an illustration is given to demonstrate the validity of our results.

1. Introduction and Preliminaries

In 2002, Branciari [8] generalized the Banach's contraction principle [6] by introducing a new concept known as the integral type of contraction, and many researchers have studied several fixed point theories for this type of contraction. For example, we refer readers to references ([1], [2], [9], [10], [11], [12], [15], [19]).

The foundational information necessary for elucidating our subsequent results is systematically compiled in this section. By assembling key elements and background details, we lay the groundwork for a comprehensive presentation that enhances the clarity and understanding of our findings.

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Theorem 1.1. [8] Let (X, d) be a complete metric space and $U : X \rightarrow X$ be a self mapping satisfying the contraction

$$\int_0^{d(Ux, Uy)} \varphi(t) dt \leq \alpha \int_0^{d(x, y)} \varphi(t) dt,$$

where $\alpha \in (0, 1)$ and $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ which is non-negative, summable on each compact subset of \mathbb{R}^+ , and such that for each $\varepsilon > 0$, $\int_0^\varepsilon \varphi(t) dt > 0$. Then U has a unique fixed point in X .

Example 1.1. [8] Let d be a Euclidean distance function, we define the map $U : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ and Lebesgue-integrable function φ as

$$U(x) = x + 1 \text{ and } \varphi(t) = -1.$$

Clearly, for some arbitrary $\alpha \in (0, 1)$, all the assumptions of Theorem 1.1 are satisfied. But the map U has no fixed point.

Definition 1.2. [16] A function $\psi : [0, \infty) \rightarrow [0, \infty)$ is called an altering distance function if the following properties are satisfied:

- 1) ψ is non-decreasing and continuous;
- 2) $\psi(t) = 0$ if and only if $t = 0$.

The concept of C-class functions, introduced by Ansari [3], represents a noteworthy generalization of the traditional Banach contraction. Ansari's innovation extends the scope of fixed-point theorems, offering a more flexible and inclusive framework. Following this, the concept of C-class functions received a great deal of attention from various researchers, resulting in a collective interest in constructing fixed-point theorems in this framework (see [5], [7], [13], [14]).

Definition 1.3. [3] A continuous function $F : [0, +\infty) \times [0, +\infty) \rightarrow \mathbb{R}$ is called C-class function if it satisfies the following conditions:

- (C1) $F(s, t) \leq s$, for all $(s, t) \in [0, +\infty) \times [0, +\infty)$;
- (C2) $F(s, t) = s$ implies that either $s = 0$ or $t = 0$.

Let us suppose that C denote the family of C-class function.

Remark 1.4. [3] Note that for some F , we have that $F(0, 0) = 0$.

Example 1.5. [3] The following functions $F : [0, +\infty) \times [0, +\infty) \rightarrow \mathbb{R}$ are elements of C , for all $s, t \in [0, +\infty)$:

- (1) $F(s, t) = s - t$;
- (2) $F(s, t) = ms$, $m \in (0, 1)$;
- (3) $F(s, t) = \frac{s}{(1+t)^r}$, $r \in [0, +\infty)$;
- (4) $F(s, t) = \frac{\log(t+a^s)}{1+t}$, $a > 1$;
- (5) $F(s, t) = \frac{\ln(t+a^s)}{2}$, $a > e$;
- (6) $F(s, t) = s - \varphi(s)$, where $\varphi : [0, +\infty) \rightarrow [0, +\infty)$ is a continuous function such that $\varphi(s) = 0 \Leftrightarrow s = 0$.

In light of the foundational groundwork and the exploration of fixed-point theorems for C-class functions, we now present the main results of our study, unveiling novel insights into the existence and uniqueness of fixed points for self-maps of integral type.

2. Mains results

Theorem 2.1. *Let U be a self mapping on a complete metric space (X, d) satisfying the contraction*

$$\psi \left(\int_0^{d(Ux, Uy)} \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{M(x, y)} \varphi(t) dt \right), \delta \left(\int_0^{M(x, y)} \varphi(t) dt \right) \right), \quad (1)$$

for all $x, y \in X$, where $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ which is nonnegative on each compact subset of \mathbb{R}^+ , such that for each $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$ and $F : [0, +\infty]^2 \rightarrow \mathbb{R}$ is a C-class function, $\psi : [0, +\infty[\rightarrow [0, +\infty[$ is an altering distance function and $\delta : [0, +\infty[\rightarrow [0, +\infty[$ is a nondecreasing and lower semi continuous such that $\delta(0) \geq 0$, and $\delta(t) > 0, \forall t > 0$, and

$$M(x, y) = k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\}, \quad (2)$$

such that $k \in (0, 1)$. Then U has a unique fixed point in X .

PROOF. Let $x_0 \in X$ be arbitrary. Define the sequence $\{x_n\}$ by $x_{n+1} = Ux_n$. For each $n \geq 1$ and from (1), we have

$$\begin{aligned} \psi \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) &= \psi \left(\int_0^{d(Ux_n, Ux_{n-1})} \varphi(t) dt \right) \\ &\leq F \left(\psi \left(\int_0^{M(x_n, x_{n-1})} \varphi(t) dt \right), \delta \left(\int_0^{M(x_n, x_{n-1})} \varphi(t) dt \right) \right), \end{aligned}$$

where

$$\begin{aligned} M(x_n, x_{n-1}) &= k \max \left\{ \begin{array}{l} d(x_n, x_{n-1}), d(x_n, Ux_n), d(x_{n-1}, Ux_{n-1}), \\ d(x_n, Ux_{n-1}), d(x_{n-1}, Ux_n) \end{array} \right\} \\ &= k \max \left\{ \begin{array}{l} d(x_n, x_{n-1}), d(x_n, x_{n+1}), d(x_{n-1}, x_n), \\ d(x_n, x_n), d(x_{n-1}, x_{n+1}) \end{array} \right\} \\ &= k \max \{d(x_n, x_{n-1}), d(x_n, x_{n+1}), d(x_{n-1}, x_{n+1})\} \\ &= k \max \{d(x_n, x_{n-1}), d(x_n, x_{n+1})\}. \end{aligned}$$

First, we suppose that $d(x_n, x_{n+1}) \geq d(x_n, x_{n-1})$ for some n , we get

$$\psi \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{kd(x_{n+1}, x_n)} \varphi(t) dt \right), \delta \left(\int_0^{kd(x_{n+1}, x_n)} \varphi(t) dt \right) \right).$$

Now, we conclude immediately that

$$\psi \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) \leq \psi \left(\int_0^{kd(x_{n+1}, x_n)} \varphi(t) dt \right),$$

which contradicts. Hence $M(x_n, x_{n-1}) = kd(x_n, x_{n-1})$, so

$$\psi \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{kd(x_n, x_{n-1})} \varphi(t) dt \right), \delta \left(\int_0^{kd(x_n, x_{n-1})} \varphi(t) dt \right) \right),$$

which conclude that

$$\psi \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) \leq \psi \left(\int_0^{kd(x_n, x_{n-1})} \varphi(t) dt \right).$$

Now, we will show that $\{x_n\}$ is a Cauchy sequence in (X, d) , for some $n \geq 1$, we have

$$\begin{aligned} \int_0^{d(x_{n+1}, x_n)} \varphi(t) dt &\leq \int_0^{kd(x_n, x_{n-1})} \varphi(t) dt \\ &\leq \int_0^{k^2 d(x_{n-1}, x_{n-2})} \varphi(t) dt \\ &\vdots \\ &\leq \int_0^{k^n d(x_1, x_0)} \varphi(t) dt. \end{aligned}$$

Taking $n \rightarrow \infty$, we get

$$\lim_{n \rightarrow \infty} \left(\int_0^{d(x_{n+1}, x_n)} \varphi(t) dt \right) = 0.$$

Consequently, it gives

$$\lim_{n \rightarrow \infty} d(x_{n+1}, x_n) = 0. \quad (3)$$

Next, we assert that the sequence $\{x_n\}$ is Cauchy. Assume not, so for $\varepsilon > 0$, there exists subsequences $\{x_{n(i)}\}$ and $\{x_{m(i)}\}$ of $\{x_n\}$ with $n(i) < m(i) < n(i+1)$ satisfying

$$d(x_{n(i)}, x_{m(i)}) \geq \varepsilon \text{ and } d(x_{n(i)}, x_{m(i-1)}) < \varepsilon. \quad (4)$$

Consider

$$\begin{aligned}
 & \psi \left(\int_0^\varepsilon \varphi(t) dt \right) \leq \psi \left(\int_0^{d(x_{n(i)}, x_{m(i)})} \varphi(t) dt \right) \\
 & = \psi \left(\int_0^{d(Ux_{n(i)-1}, Ux_{m(i)-1})} \varphi(t) dt \right) \\
 & \leq F \left(\psi \left(\int_0^{M(x_{n(i)-1}, x_{m(i)-1})} \varphi(t) dt \right), \delta \left(\int_0^{M(x_{n(i)-1}, x_{m(i)-1})} \varphi(t) dt \right) \right), \quad (5)
 \end{aligned}$$

from (2), we find

$$\begin{aligned}
 & M(x_{n(i)-1}, x_{m(i)-1}) \\
 & = k \max \{ d(x_{n(i)-1}, x_{m(i)-1}), d(x_{n(i)-1}, Ux_{n(i)-1}), d(x_{m(i)-1}, Ux_{m(i)-1}), \\
 & \quad d(x_{n(i)-1}, Ux_{m(i)-1}), d(x_{m(i)-1}, Ux_{n(i)-1}) \} \\
 & = k \max \{ d(x_{n(i)-1}, x_{m(i)-1}), d(x_{n(i)-1}, x_{n(i)}), d(x_{m(i)-1}, x_{m(i)}), \\
 & \quad d(x_{n(i)-1}, x_{m(i)}), d(x_{m(i)-1}, x_{n(i)}) \},
 \end{aligned}$$

where

$$\begin{aligned}
 & \int_0^{M(x_{n(i)-1}, x_{m(i)-1})} \varphi(t) dt \\
 & = \int_0^{k \max \{ d(x_{n(i)-1}, x_{m(i)-1}), d(x_{n(i)-1}, x_{n(i)}), d(x_{m(i)-1}, x_{m(i)}), d(x_{n(i)-1}, x_{m(i)}), d(x_{m(i)-1}, x_{n(i)}) \}} \varphi(t) dt \\
 & = \max \left\{ \int_0^{kd(x_{n(i)-1}, x_{m(i)-1})} \varphi(t) dt, \int_0^{kd(x_{n(i)-1}, x_{n(i)})} \varphi(t) dt, \int_0^{kd(x_{m(i)-1}, x_{m(i)})} \varphi(t) dt, \right. \\
 & \quad \left. \int_0^{kd(x_{n(i)-1}, x_{m(i)})} \varphi(t) dt, \int_0^{kd(x_{m(i)-1}, x_{n(i)})} \varphi(t) dt \right\}.
 \end{aligned}$$

By using (4) and triangle inequality, we find

$$\begin{aligned}
 kd(x_{n(i)-1}, x_{m(i)-1}) & \leq kd(x_{n(i)-1}, x_{n(i)}) + kd(x_{n(i)}, x_{m(i)-1}) \\
 & \leq kd(x_{n(i)-1}, x_{n(i)}) + k\varepsilon, \\
 \lim_{i \rightarrow \infty} \int_0^{kd(x_{n(i)-1}, x_{m(i)-1})} \varphi(t) dt & \leq \int_0^{k\varepsilon} \varphi(t) dt, \quad (6)
 \end{aligned}$$

and

$$\begin{aligned}
 kd(x_{n(i)-1}, x_{m(i)}) & \leq kd(x_{n(i)-1}, x_{n(i)}) + kd(x_{n(i)}, x_{m(i)}) \\
 & \leq kd(x_{n(i)-1}, x_{n(i)}) + kd(x_{n(i)}, x_{m(i)-1}) + kd(x_{m(i)-1}, x_{m(i)}) \\
 & \leq kd(x_{n(i)-1}, x_{n(i)}) + k\varepsilon + kd(x_{m(i)-1}, x_{m(i)}),
 \end{aligned}$$

taking i to infinity and using (3), we have

$$\lim_{i \rightarrow \infty} \int_0^{kd(x_{n(i)-1}, x_{m(i)})} \varphi(t) dt \leq \int_0^{k\varepsilon} \varphi(t) dt, \quad (7)$$

form (4), we get

$$\int_0^{kd(x_{m(i)-1}, x_{n(i)})} \varphi(t) dt \leq \int_0^{k\varepsilon} \varphi(t) dt. \quad (8)$$

Taking i to infinity in inequality (5) and using (6),(7),(8), we get

$$\psi \left(\int_0^\varepsilon \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{k\varepsilon} \varphi(t) dt \right), \delta \left(\int_0^{k\varepsilon} \varphi(t) dt \right) \right).$$

So,

$$\psi \left(\int_0^\varepsilon \varphi(t) dt \right) \leq \psi \left(\int_0^{k\varepsilon} \varphi(t) dt \right)$$

this is a contradiction. Therefore $\{x_n\}$ is a Cauchy sequence. Call the limit as x such that $\lim_{n \rightarrow \infty} x_n = x$, i.e

$$\lim_{n \rightarrow \infty} Ux_n = x,$$

Next, assert that x is a fixed point of U , consider

$$\lim_{n \rightarrow \infty} \psi \left(\int_0^{d(Ux_n, Ux)} \varphi(t) dt \right) \leq \lim_{n \rightarrow \infty} F \left(\psi \left(\int_0^{M(x_n, x)} \varphi(t) dt \right), \delta \left(\int_0^{M(x_n, x)} \varphi(t) dt \right) \right) \quad (9)$$

where

$$\lim_{n \rightarrow \infty} M(x_n, x) = \lim_{n \rightarrow \infty} k \max \{d(x_n, x), d(x_n, Ux_n), d(x, Ux), d(x_n, Ux), d(x, Ux_n)\}.$$

Then

$$\lim_{n \rightarrow \infty} M(x_n, x) = kd(x, Ux).$$

From (9), we get

$$\begin{aligned} \psi \left(\int_0^{d(x, Ux)} \varphi(t) dt \right) &\leq F \left(\psi \left(\int_0^{kd(x, Ux)} \varphi(t) dt \right), \delta \left(\int_0^{kd(x, Ux)} \varphi(t) dt \right) \right) \\ &\leq \psi \left(\int_0^{kd(x, Ux)} \varphi(t) dt \right), \end{aligned}$$

this is a contradiction. This implies $d(x, Ux) = 0$. Thus $Ux = x$. This proves that x is a fixed point of U . For the uniqueness, assume that there is another point y such that $Uy = y$, from (1), we have

$$\psi \left(\int_0^{d(Uy, Ux)} \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{M(y, x)} \varphi(t) dt \right), \delta \left(\int_0^{M(y, x)} \varphi(t) dt \right) \right),$$

where

$$\begin{aligned} M(y, x) &= k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\} \\ &= kd(x, y). \end{aligned}$$

Thus

$$\begin{aligned} \psi \left(\int_0^{d(Uy, Ux)} \varphi(t) dt \right) &= \psi \left(\int_0^{d(y, x)} \varphi(t) dt \right) \\ &\leq F \left(\psi \left(\int_0^{kd(x, y)} \varphi(t) dt \right), \delta \left(\int_0^{kd(x, y)} \varphi(t) dt \right) \right). \end{aligned}$$

Thus

$$\psi \left(\int_0^{d(Uy, Ux)} \varphi(t) dt \right) \leq \psi \left(\int_0^{kd(x, y)} \varphi(t) dt \right).$$

This is a contradiction. Therefore $x = y$. Hence x is the unique fixed point of U . \square

As a direct consequence of our main results, we derive the following corollaries

Corollary 2.2. *Let U be a self mapping on a complete metric space (X, d) , satisfying the contraction*

$$\psi \left(\int_0^{d(Ux, Uy)} \varphi(t) dt \right) \leq \alpha \psi \left(\int_0^{M(x, y)} \varphi(t) dt \right),$$

for $0 < \alpha < 1$, for all $x, y \in X$, where $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ which is nonnegative on each compact subset of \mathbb{R}^+ , and such that for each $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$, and $\psi : [0, +\infty[\rightarrow [0, +\infty[$ is an altering distance function, and

$$M(x, y) = k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\}$$

such that $k \in (0, 1)$. Then U has a unique fixed point in X .

PROOF. Put $F(s, t) = ms$, where $m \in (0, 1)$ in Theorem 2.1, we get the result \square

Corollary 2.3. *Let U be a self mapping on a complete metric space (X, d) , satisfying the contraction*

$$\psi \left(\int_0^{d(Ux, Uy)} \varphi(t) dt \right) \leq \psi \left(\int_0^{M(x, y)} \varphi(t) dt \right) - \delta \left(\int_0^{M(x, y)} \varphi(t) dt \right),$$

for all $x, y \in X$, where $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ which is nonnegative on each compact subset of \mathbb{R}^+ , and such that for each $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$, and $\psi : [0, +\infty[\rightarrow [0, +\infty[$ is an altering distance function and $\delta : [0, +\infty[\rightarrow [0, +\infty[$ is a nondecreasing and lower semi continuous such that $\delta(0) \geq 0$, and $\delta(t) > 0, \forall t > 0$, and $M(x, y) =$

$k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\}$, such that $k \in (0, 1)$.
Then U has a unique fixed point in X .

PROOF. Put $F(s, t) = s - t$, in Theorem 2.1, we get the result. \square

Corollary 2.4. *Let U be a self mapping on a complete metric space (X, d) , satisfying the contraction*

$$\psi \left(\int_0^{d(Uy, Ux)} \varphi(t) dt \right) \leq \frac{\psi \left(\int_0^{M(y, x)} \varphi(t) dt \right)}{1 + \delta \left(\int_0^{M(y, x)} \varphi(t) dt \right)},$$

for all $x, y \in X$, where $\varphi : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ which is nonnegative on each compact subset of \mathbb{R}^+ , and such that for each $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$, and $\psi : [0, +\infty[\rightarrow [0, +\infty[$ is an altering distance function and $\delta : [0, +\infty[\rightarrow [0, +\infty[$ is a nondecreasing and lower semi continuous such that $\delta(0) \geq 0$, and $\delta(t) > 0, \forall t > 0$, and $M(x, y) = k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\}$, such that $k \in (0, 1)$.
Then U has a unique fixed point in X .

PROOF. Put $F(s, t) = \frac{s}{(1+t)^r}$, and assume $r = 1$ in Theorem 2.1, we obtain the result. \square

To illustrate the practical implications of our main results, we present a compelling example that demonstrates the application of the derived fixed-point theorems for C-class functions in a specific mathematical context. The theoretical findings are concretized through this example.

Example 2.1. Let $X = [0, 1]$ and $d(x, y) = |x - y|$. We take $U : X \rightarrow X$ by

$$Ux = \frac{1}{2}x.$$

Define $F : [0, +\infty)^2 \rightarrow \mathbb{R}$ as

$$F(s, t) = ms \text{ with } m = \frac{3}{4} \in (0, 1),$$

then F is a C-class function (from Example 1.5). Let as define $\psi, \varphi : [0, +\infty) \rightarrow [0, +\infty)$ by $\psi(t) = t$ and $\varphi(t) = \frac{t}{3}$. Then, for each $\epsilon > 0$,

$$\int_0^\epsilon \varphi(t) dt = \frac{\epsilon^2}{6} > 0$$

and

$$M(x, y) = k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\}$$

such that

$$0 < k = \frac{1}{\sqrt{2}} < 1.$$

We can verify the contraction of Theorem 2.1. If $x = y$ for all $x, y \in X$, then result holds trivially. So suppose that $x \neq y$ for all $x, y \in X$, we get

$$d(x, y) = 1, \quad d(x, Ux) = 0, \quad d(y, Uy) = \frac{1}{2}, \quad d(x, Uy) = \frac{1}{2}, \quad d(y, Ux) = 1,$$

we obtain

$$\begin{aligned} M(x, y) &= k \max \{d(x, y), d(x, Ux), d(y, Uy), d(x, Uy), d(y, Ux)\} \\ &= \frac{1}{\sqrt{2}} \end{aligned}$$

and

$$\begin{aligned} \psi \left(\int_0^{d(Ux, Uy)} \varphi(t) dt \right) &= \int_0^{|Ux-Uy|} \frac{t}{3} dt \\ &= \frac{1}{24}. \end{aligned}$$

So

$$\begin{aligned} F \left(\psi \left(\int_0^{M(x,y)} \varphi(t) dt \right), \delta \left(\int_0^{M(x,y)} \varphi(t) dt \right) \right) &= m \psi \left(\int_0^{M(x,y)} \varphi(t) dt \right) \\ &= m \int_0^{M(x,y)} \varphi(t) dt = \frac{1}{16}. \end{aligned}$$

Then clearly

$$\psi \left(\int_0^{d(Ux, Uy)} \varphi(t) dt \right) \leq F \left(\psi \left(\int_0^{M(x,y)} \varphi(t) dt \right), \delta \left(\int_0^{M(x,y)} \varphi(t) dt \right) \right).$$

Hence, all the conditions of the Theorem 2.1 are verified and 0 is the unique fixed point of the map U .

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